

## 11

1. (6 )

$$a_1 = \frac{v}{t_1},$$

— ,  $t_1$  —  
.

$$a_2 = \frac{v^2}{R}, \quad R -$$

$$, \quad v = \frac{\pi R}{t_2}, \quad a_2 = \frac{v \pi}{t_2}.$$

$$, \quad \frac{v}{t_1} = \frac{v \pi}{t_2},$$

$$\frac{t_2}{t_1} = \pi .$$

$$: \frac{t_2}{t_1} = \pi .$$

2. (10 )

$$V_0 = gt ,$$

$$\beta = 90^\circ - 2\alpha$$

.) . (

$$, \dots v_x = V_0 \cos \beta = \text{const} .$$

$$E_0 = mgH ,$$

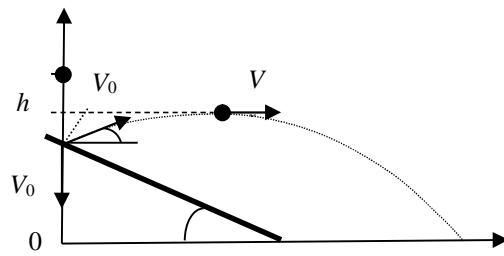
$$E_1 = mgh + \frac{mv_x^2}{2} .$$

$$E_1 = E_0 \quad mgh + \frac{mv_x^2}{2} = mgH .$$

$$v_x = V_0 \cos \beta = gt \cos \beta = gt \sin 2\alpha ,$$

$$H = h + \frac{gt^2 \sin^2 2\alpha}{2} .$$

:  $H = 2$  .



3(10) .

$$pV \text{ - } (p_1, V_1) \text{ } (p_2, V_2) \text{ } T_1, T_2$$

:  $Q = \Delta U_{12} + A_{12}$  .

$$\begin{cases} pV = \nu RT, \\ U = \frac{3}{2} \nu RT. \end{cases}$$

$$\Delta U_{12} = \frac{3}{2} \nu R(T_2 - T_1) = \frac{3}{2} (p_2 V_2 - p_1 V_1)$$

$pV$  - , . . .

$$A_{12} = \frac{1}{2} (p_2 V_2 - p_1 V_1)$$

$$Q = \Delta U_{12} + A_{12} = 2(p_2 V_2 - p_1 V_1)$$

$$\frac{p_2}{p_1} = \frac{V_2}{V_1}, \quad \frac{p_2 V_2}{p_1 V_1} = \left(\frac{V_2}{V_1}\right)^2$$

$$Q = 2p_1 V_1 \left(\frac{V_2^2}{V_1^2} - 1\right) = 2\nu RT_1 \left(\frac{V_2^2}{V_1^2} - 1\right)$$

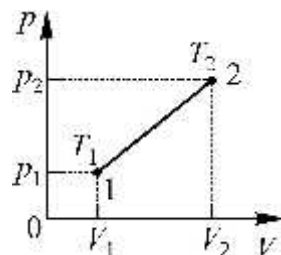
6.

$$\alpha = \frac{\rho_1}{\rho_2} = \frac{m/V_1}{m/V_2} = \frac{V_2}{V_1}$$

$$Q = 2\nu RT_1 \left(\frac{V_2^2}{V_1^2} - 1\right) = 2\nu RT_1 (\alpha^2 - 1)$$

$$T_1 = \frac{Q}{2\nu R(\alpha^2 - 1)}$$

:  $T_1 \approx 400$  .



4. (8) )

$$W_3 = \frac{C_1 U^2}{2}. \quad (1)$$

1:

$$q = C_1 U. \quad (2)$$

:

$$W_{31} + W_{32} = \frac{C_1 U_1^2}{2} + \frac{C_2 U_2^2}{2}. \quad (3)$$

2

1

$$W = W_1 + W_2. \quad (4)$$

$$q = q_1 + q_2 = C_1 U_1 + C_2 U_2. \quad (5)$$

(1) - (5),

$$\begin{cases} C_1 U^2 = C_1 U_1^2 + C_2 U_2^2, \\ C_1 U = C_1 U_1 + C_2 U_2. \end{cases}$$

$$C_1 = \frac{C_2 U_2}{2U - U_2}.$$

:  $\epsilon_1 = 0,5$  .

5. (10) )

$$l_1, \\ m = l_1 S_{\dots 1}.$$

$$l_2. \\ m_2 = l_2 S_{\dots 2}.$$

$$: l_{1\dots 1} S = l_2 S_{\dots 2}. \quad : \dots_1 = \dots_2 \frac{l_2}{l_1}.$$