

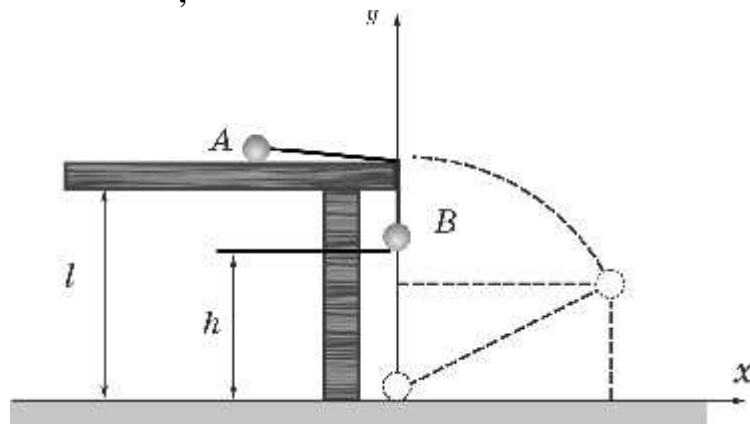
1.

$$2m \frac{v_0^2}{2} = mgh = \frac{2}{3} mgl, \quad v_0 = \sqrt{\frac{2}{3} gl}. \quad (1)$$

$$a_u = \frac{v_0^2}{l},$$

$$mg : m \frac{v_0^2}{l} = mg + T. \quad (2)$$

$$(2) \quad v_0 \quad (1), \quad : T = -mg / 3,$$



$$t: x = v_0 t, \quad y = l - \frac{gt^2}{2}. \quad (3)$$

$$x^2 + y^2 = l^2. \quad (4)$$

$$(4) \quad (3),$$

$$v_0^2 t^2 + \left(l - \frac{gt^2}{2} \right)^2 = l^2, \quad (1), \quad gt^2 \left(\frac{gt^2}{4} - \frac{l}{3} \right) = 0$$

$$t^2 = \frac{4l}{3g} \quad t=0$$

$$A \quad t^2 \quad (3),$$

$$: y = \frac{l}{3}.$$

2.

$$mgh = \frac{mv_0^2}{2},$$

$$h = \frac{v_0^2}{2g}.$$

$$0 = mv_1 - mv_2.$$

$$(\quad),$$

$$v_1 = v_2 = v.$$

$$mgh + \frac{mv^2}{2} = \frac{mu^2}{2}$$

$$v = \sqrt{u^2 - 2gh} = \sqrt{u^2 - v_0^2}$$

$$v_0^2 = 2gh.$$

$$u = v + gt_1 \quad \text{и} \quad u = -v + gt_2.$$

$$t_1 = \frac{u - \sqrt{u^2 - v_0^2}}{g}, \quad t_2 = \frac{u + \sqrt{u^2 - v_0^2}}{g}$$

$$\Delta t = t_2 - t_1 = \frac{2}{g} \sqrt{u^2 - v_0^2}$$

$$\Delta t = 30.$$

3.

1³

v_1

v_2

$$V = 1 \text{ м}^3$$

$$v = v_1 + v_2 = \frac{pV}{RT} = \frac{0,9 \cdot 10^5 \cdot 1}{8,31 \cdot 271} \approx 40.$$

$$m = m_1 + m_2 = m_1 v_1 + m_2 v_2 = \rho V = 0,44 \text{ кг.}$$

$$v_1 + v_2 = 40, 4 \cdot 10^{-3} v_1 + 32 \cdot 10^{-3} v_2 = 0,44,$$

$$: v_1 = 30 \quad , \quad v_2 = 10$$

$$v_3 = 35$$

$$\frac{p}{\rho_3} = \frac{v}{v_3} = \frac{40}{35} \Rightarrow p_3 = \frac{\rho v_3}{v} = 0,79 \cdot 10^5 \text{ Па.}$$

4.

$$qE = \frac{kq^2}{x^2},$$

$$x = \sqrt{\frac{kq}{E}}$$

$$x < R \quad . \quad qE > kq^2 / R^2$$

$$: \frac{2mv^2}{2} - \frac{kq^2}{R} = qE(R - x) - \frac{kq^2}{x}.$$

$$v = \sqrt{\frac{qE}{mR} \left(R - \sqrt{\frac{kq}{E}} \right)}.$$

$$\sqrt{\frac{kq}{E}} > R,$$

« »,

5.

$$: P_1 = mg - F_{A1} = P - \rho_1 gV, \quad \rho_1 \text{ —}$$

$$: P_2 = mg - F_{A2} = P - \rho_2 gV, \quad \rho_2$$

$$: \begin{cases} P - P_1 = \rho_1 gV \\ P - P_2 = \rho_2 gV \end{cases} \Rightarrow \frac{P - P_1}{P - P_2} = \frac{\rho_1 gV}{\rho_2 gV} \Rightarrow \rho_2 = \frac{(P - P_2) \rho_1}{P - P_1}.$$