

1.

$$K_1 = \frac{mv^2}{2} + \frac{2mv^2}{2}. \quad (1)$$

V

$$K_2 = \frac{2mV^2}{2}. \quad (2)$$

$$Q = K_1 - K_2.$$

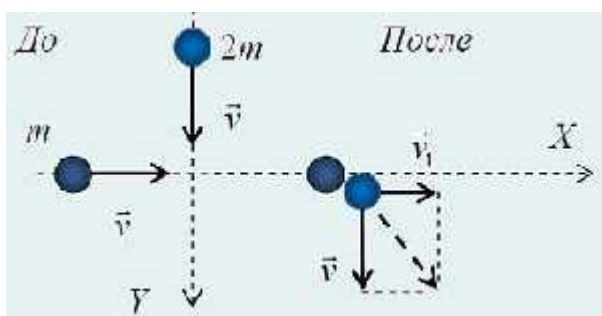
$$\alpha = Q / K = (K_1 - K_2) / K.$$

(1) (2)

$$\alpha = \left(\frac{mv^2}{2} + \frac{2mv^2}{2} - \frac{2mV^2}{2} \right) / \left(\frac{mv^2}{2} \right).$$

$$\alpha = \left(\frac{v^2}{2} + v^2 - V^2 \right) / \left(\frac{v^2}{2} \right). \quad (3)$$

(. .).



$$V = \sqrt{(v_1^2 + v^2)}. \quad (4)$$

$$mv = 2mv_1,$$

$$v_1 = \frac{v}{2}.$$

y ,

v.

(4)

$$V = \sqrt{\left(\frac{v}{2}\right)^2 + v^2} = v\sqrt{\frac{5}{4}}.$$

(3)

$$\alpha = \left(\frac{v^2}{2} + v^2 - \frac{5}{4}v^2 \right) / \left(\frac{v^2}{2} \right).$$

$$= 0,5 \quad 50\%.$$

$$\therefore = 50\%.$$

2.

$$a = g(\sin \alpha - k \cos \alpha) \quad (1)$$

(. . .):

$$ma = mg \sin \alpha - (p_1 - p_2) S \quad (2)$$

$$p_1 V_1 = pV \quad (3)$$

$$p_2 V_2 = pV \quad (4)$$

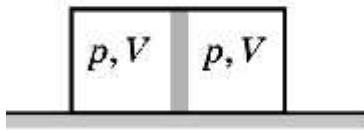


Рис. 1

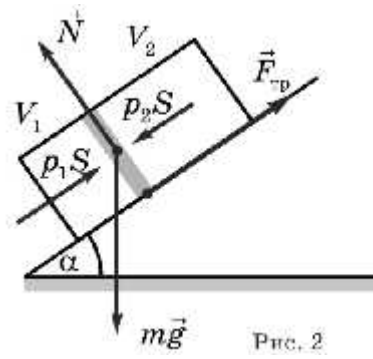


Рис. 2

(1) - (4) , $V_1 + V_2 = 2V$

V_2 / V_1 :

$$V_2 / V_1 = \frac{kmg \cos \alpha}{\rho S} + \sqrt{\left(\frac{kmg \cos \alpha}{\rho S}\right)^2 + 1} \approx 1,2$$

: $V_2 / V_1 \approx 1,2$.

3.

1.

$\Phi_A > \Phi_B$,

R_2 ,

1.

$R_0 = R_1 + R_2$,

$P_1 = \frac{\varepsilon^2}{R_1 + R_2} \cdot (1)$

2.

R_2

$\Phi_A < \Phi_B$,

2.

). $P_2 = \frac{\varepsilon^2}{R_1} \cdot (2)$

3.

(1) (2),

, $R_2 = 20$.

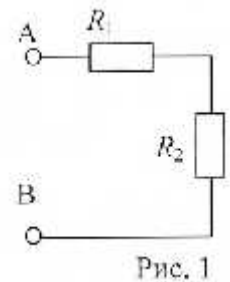


Рис. 1

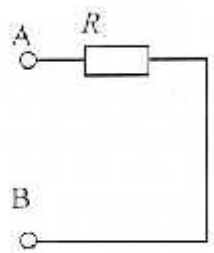


Рис. 2

, : $R_1 = 10$

4.

$$\frac{mv_1^2}{2} + mg \frac{h}{2} = \frac{mv_2^2}{2}, \quad v_1 = \text{const.}$$

$$m\vec{g} + \vec{F}_A = 0 \quad (1)$$

$$\left\{ \begin{array}{l} F_A = |BIl| \\ I = \frac{\varepsilon_i}{R} \\ \varepsilon_i = \left| -\frac{\Phi_1}{\Delta t} \right| = l v_1 B \end{array} \right., \quad l = a$$

1 2

$$F_A = \frac{l^2 B^2 v_1}{R}, \quad mg = \frac{l^2 B^2 v_1}{R} \Rightarrow v_1 = \frac{mgR}{l^2 B^2}$$

$$\frac{m \left[\frac{mgR}{l^2 B^2} \right]^2}{2} + mg \frac{h}{2} = \frac{mv_2^2}{2} \Rightarrow v_2 = \sqrt{2lg + \frac{m^2 g^2 R^2}{l^4 B^4}}$$

5.

« » .

$NT_1 = (N-1)T_2$, N

(), N

: $T_2 = \frac{N}{N-1} T_1$