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$\vec{u}$ (. 1).

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$\vec{v}_0$.
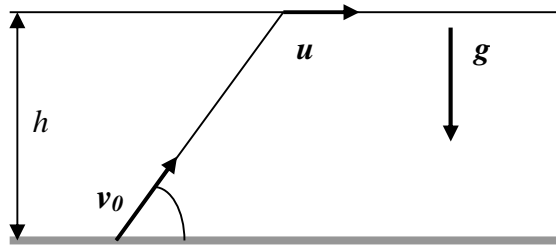
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$$h = t \cdot v_0 \sin\Gamma - \frac{gt^2}{2} \quad (1) \qquad\qquad t^2 - \frac{2v_0 \sin\Gamma}{g} \cdot t + \frac{2h}{g} = 0$$
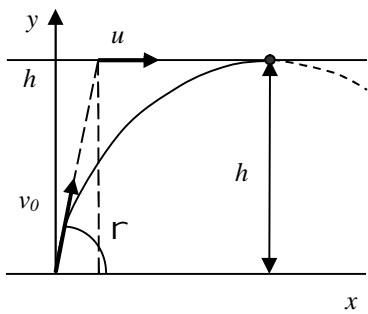
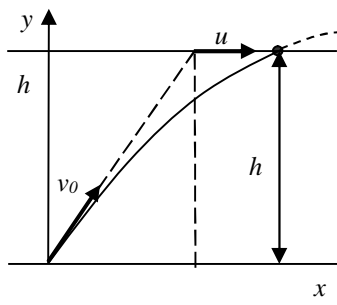$$t_{1,2} = \frac{v_0 \sin\Gamma}{g} \pm \frac{\sqrt{v_0^2 \sin^2\Gamma - 2gh}}{g}$$

:

1). $t_1 = t_2 = \dfrac{v_0 \sin\Gamma}{g}$ (.   .2)   2). $t = \dfrac{v_0 \sin\Gamma}{g} - \dfrac{\sqrt{v_0^2 \sin^2\Gamma - 2gh}}{g}$ (.   .3)

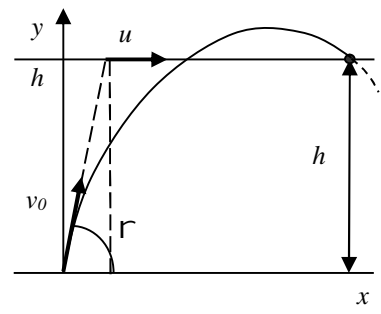3). $t = \dfrac{v_0 \sin\Gamma}{g} + \dfrac{\sqrt{v_0^2 \sin^2\Gamma - 2gh}}{g}$ (.   .4)

.2   .3   .4

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$$v_0^2 \sin^2 \Gamma = 2gh \qquad h = \frac{v_0^2 \sin^2 \Gamma}{2g} \quad (2)$$

$$t = \frac{v_0 \sin \Gamma}{g}$$

, t

$$v_0 \cos \Gamma \cdot t = h \cdot ctg\Gamma + ut$$

$$v_0 \cos \Gamma \cdot \frac{v_0 \sin \Gamma}{g} = h \cdot ctg\Gamma + u \frac{v_0 \sin \Gamma}{g}$$

$$v_0 \cos \Gamma = 2u$$

$$v_0 \cos \Gamma > 2u$$

$$v_0 \cos \Gamma \cdot t = h \cdot ctg\Gamma + ut$$

$$t = \frac{h \cdot ctg\Gamma}{v_0 \cos \Gamma - u}$$

t (1),   :

$$h = \frac{2u}{g} tg^2\Gamma \ (v_0 \cos \Gamma - u) \qquad (3)$$

$v_0 \cos \Gamma < 2u$.   ,   .4.
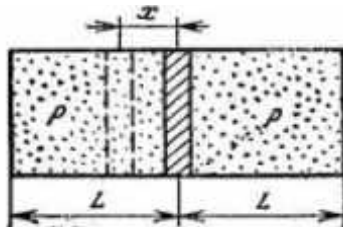
(3).

$v_0 \cos \Gamma = 2u$ (3)   (2).

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                                                            $2L$ S (. 5).

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$$p_1 = nkT$$

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1). $pS \leq F$, $x = 0$

2). x .1,

$L + x$.

$$pL = p_2(L + x)$$

$p -$, $p_2 -$.

$$F - p_2 S = 0$$

$$x = L \cdot \left(\frac{pS}{F} - 1 \right) \quad (1)$$

, $pS = 2F$ $1 \quad x = L$

, , $pS \geq 2F$ $x = L$,

p (1)

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2-3 (. 6).

$\sqrt{T}$.

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1-2 $p \sim T$. —

$p \sim T$ $V = $ const. , 1-2 ,

$$C_V = \frac{3}{2} R .$$

2-3 $p \sim \sqrt{T}$. —

$(\mathcal{E} = 1)$

$$V = \frac{RT}{p} \sim \sqrt{T}$$

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$pV -$ (. 7), , .

ΔU A .
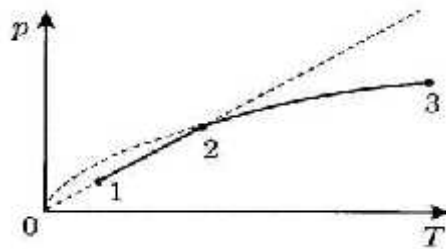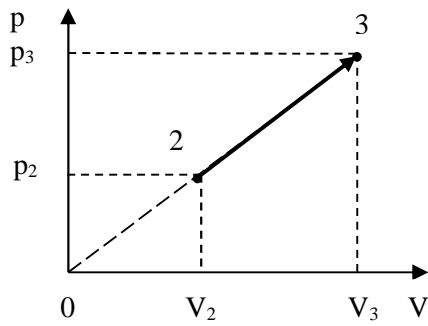
2 3 p_2, V_2 p_3, V_3 .

ΔQ, 2-3,
:

$$\Delta Q = \Delta U + A = \frac{3}{2} R\left(T_3 - T_2\right) + \frac{1}{2}\left(p_3 + p_2\right)\cdot\left(V_3 - V_2\right)$$

$$\Delta Q = \frac{3}{2} R\left(T_3 - T_2\right) + \frac{1}{2}\left(RT_3 - RT_2 + p_2V_3 - p_3V_2\right)$$

— , $p_2V_2 = RT_2$ $P_3V_3 = RT_3.$

,

$$\frac{p_2}{V_2} = \frac{p_3}{V_3}$$

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$$\Delta Q = 2R\left(T_3 - T_2\right)$$

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. $2R$.

$$C_{23} = 2R$$

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, $C,$, R $2R$
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. U_0 .
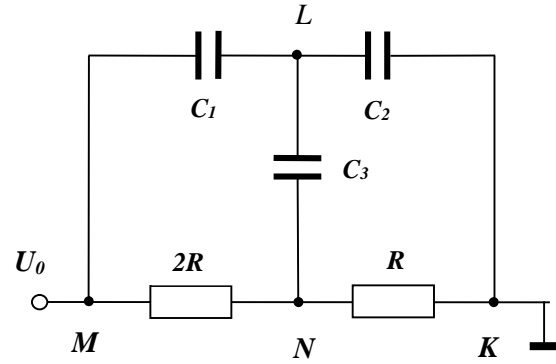
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$$U_M = U_0 \qquad U_N = \frac{U_0}{3} \qquad U_K = 0$$

$$C_1 = C_2 = C_3 = C$$

, L,

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$$q_1 + q_2 + q_3 = 0$$

$C_2 \qquad U_2$.

$$C(U_0 - U_2) = q_1 \qquad CU_2 = q_2 \qquad C(U_2 - U_0/3) = q_3$$

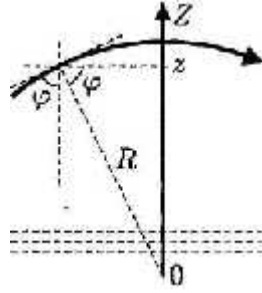$$C(U_0 - U_2) + q_2 + C(U_2 - U_0/3) = 0$$

$$q_2 = -\frac{2}{3}CU_0$$

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$\{$ –   Z   .   ,
                         , $\{$ z.

$$n(z)\sin\{ = const.$$

$\sin\{ = \dfrac{z}{R}$,   :

$$n(z) = \frac{const}{\sin\{} = \frac{R \cdot const}{z} = \frac{k}{z}$$

    k –   .   ,   ,
                                                        ,
                        z,   .

                             – 80.   .
60   .   ,   .
50   . $n(z)\sin\{ = const$
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